***Giving the task for drone to do*:**

For this problem we have multiple proposed solutions. Among them we have:

\* Magic wand solution,

\* Voice recognition solution

**Problems:**

How to identify object that drone needs to carry...

**Solution:**

“Magic wand” solution is kind of a pointer, a stick with location tag on it's tip (and for example rfId and/or barcode reader). When giving the target, you can touch the object that you want to be transported and press a button. This will initiate location calculating algorithm, read the rfId of the object and send the task to the drone.

In order to define destination – this can be done by voice commands (like the second way of identifying the object). In case of identifying the object with voice commands – voice recognition software will associate it with the appropriate rfId and send the querry to the inventory database which will give the closest position to the drone.

For target, it can be a specific module or a person. In persons case – we can track a specific astronauts tag in order to bring an object to him. In case of specific place – we can have a database of “well known locations”.